OPERATING INSTRUCTIONS

UC40

Ultrasonic sensor





Described product

UC40

Manufacturer

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Original document

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1 About this document

1.1 Information on the operating instructions

These operating instructions provide important information on how to use devices from SICK AG.

Prerequisites for safe work are:

- Compliance with all safety notes and handling instructions supplied.
- Compliance with local work safety regulations and general safety regulations for device applications

The operating instructions are intended to be used by qualified personnel and electrical specialists.

i NOTE

Read these operating instructions carefully to familiarize yourself with the device and its functions before commencing any work.

The operating instructions are an integral part of the product. Store the instructions in the immediate vicinity of the device so they remain accessible to staff at all times. Should the device be passed on to a third party, these operating instructions should be handed over with it.

These operating instructions do not provide information on the handling and safe operation of the machine or system in which the device is integrated. Information on this can be found in the operating instructions for the machine or system.

1.2 Explanation of symbols

Warnings and important information in this document are labeled with symbols. Signal words introduce the instructions and indicate the extent of the hazard. To avoid accidents, damage, and personal injury, always comply with the instructions and act carefully.



DANGER

... indicates a situation of imminent danger, which will lead to a fatality or serious injuries if not prevented.



WARNING

... indicates a potentially dangerous situation, which may lead to a fatality or serious injuries if not prevented.

CAUTION

... indicates a potentially dangerous situation, which may lead to minor/slight injuries if not prevented.

NOTICE

... indicates a potentially harmful situation, which may lead to material damage if not prevented.

NOTE

i

... highlights useful tips and recommendations as well as information for efficient and trouble-free operation.

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1.3 Further information

More information can be found on the product page.

The page can be accessed via the SICK Product ID: pid.sick.com/{P/N}/{S/N}

{P/N} corresponds to the part number of the product, see type label.

{S/N} corresponds to the serial number of the product, see type label (if indicated).

The following information is available depending on the product:

- Data sheets
- This document in all available language versions
- CAD files and dimensional drawings
- Certificates (e.g., declaration of conformity)
- Other publications
- Software
- Accessories

2 Safety information

2.1 Intended use

The UC40 ultrasonic sensor is used for non-contact detection and distance measurement. Detection and distance measurement below the operating range of the device is not possible.

SICK AG assumes no liability for losses or damage arising from the use of the product, either directly or indirectly. This applies in particular to use of the product that does not conform to its intended purpose and is not described in this documentation.

2.2 Improper use

Any use outside of the stated areas, in particular use outside of the technical specifications and the requirements for intended use, will be deemed to be incorrect use.

- The device does not constitute a safety component in accordance with the respective applicable safety standards for machines.
- The device must not be used in explosion-hazardous areas, in corrosive environments or under extreme environmental conditions.
- Any use of accessories not specifically approved by SICK AG is at your own risk.



WARNING

Danger due to improper use!

Any improper use can result in dangerous situations.

Therefore, observe the following information:

- Product should be used only in accordance with its intended use.
- All information in the documentation must be strictly observed.
- Shut down the product immediately in case of damage.

2.3 Cybersecurity

Overview

To protect against cybersecurity threats, it is necessary to continuously monitor and maintain a comprehensive cybersecurity concept. A suitable concept consists of organizational, technical, procedural, electronic, and physical levels of defense and considers suitable measures for different types of risks. The measures implemented in this product can only support protection against cybersecurity threats if the product is used as part of such a concept.

You will find further information at www.sick.com/psirt, e.g.:

- General information on cybersecurity
- Contact option for reporting vulnerabilities
- Information on known vulnerabilities (security advisories)

2.4 Limitation of liability

Relevant standards and regulations, the latest technological developments, and our many years of knowledge and experience have all been taken into account when compiling the data and information contained in these operating instructions. The manufacturer accepts no liability for damage caused by:

- Non-adherence to the product documentation (e.g., operating instructions)
- Incorrect use
- Use of untrained staff

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- Unauthorized conversions or repair
- Technical modifications
- Use of unauthorized spare parts, consumables, and accessories

2.5 Modifications and conversions

NOTICE



Modifications and conversions to the device may result in unforeseeable dangers.

Interrupting or modifying the device or SICK software will invalidate any warranty claims against SICK AG. This applies in particular to opening the housing, even as part of mounting and electrical installation.

2.6 Requirements for skilled persons and operating personnel



Risk of injury due to insufficient training.

Improper handling of the device may result in considerable personal injury and material damage.

All work must only ever be carried out by the stipulated persons.

The following qualifications are required for various activities:

Table 1: Activities and technical requirements

Activities	Qualification
Mounting, maintenance	Basic practical technical trainingKnowledge of the current safety regulations in the workplace
Electrical installation, device replacement	 Practical electrical training Knowledge of current electrical safety regulations Knowledge of the operation and control of the devices in their particular application
Commissioning, configura- tion	 Basic knowledge of the computer operating system used Basic knowledge of the design and setup of the described connections and interfaces Basic knowledge of data transmission
Operation of the device for the particular application	 Knowledge of the operation and control of the devices in their particular application Knowledge of the software and hardware environment for the particular application

2.7 Operational safety and specific hazards

Please observe the safety notes and the warnings listed here and in other sections of this product documentation to reduce the possibility of risks to health and avoid dangerous situations.

WARNING

Electrical voltage!

Electrical voltage can cause severe injury or death.

- Work on electrical systems must only be performed by qualified electricians.
- The power supply must be disconnected when attaching and detaching electrical connections.
- The product must only be connected to a voltage supply as set out in the requirements in the operating instructions.
- National and regional regulations must be complied with.
- Safety requirements relating to work on electrical systems must be complied with.

WARNING

Risk of injury and damage caused by potential equalization currents!

Improper grounding can lead to dangerous equipotential bonding currents, which may in turn lead to dangerous voltages on metallic surfaces, such as the housing. Electrical voltage can cause severe injury or death.

- Work on electrical systems must only be performed by qualified electricians.
- Follow the notes in the operating instructions.
- Install the grounding for the product and the system in accordance with national and regional regulations.

3 Product description

3.1 Scope of delivery

Scope of delivery

No. of units	Component	Note
1	Device in the version ordered	-
1	Terminal bracket	-
1	Printed safety notes, multilingual	Brief information and general safety notes

Further topics

• Accessories

The actual scope of delivery may differ for special designs, additional orders or due to the latest technical changes.

3.2 Type code

Type code structure

UC40 - a b c d e f

Position	Description	Characteristic
а	Generation	1: 1. Generation
b	Principle of operation	1: Button operation
С	Operating range	2: 65 mm 350 mm 3: 200 mm 1,300 mm 4: 350 mm 3,400 mm
d	Connection technology	1: male connector, M12, 5-pin
е	Housing material	1: PA66 plastic
f	Output function	 B: 1 output 1 push-pull digital output with IO-Link 1.1 H: 2 outputs 1 push-pull digital output with IO-Link 1.1 1 analog output (current and voltage) or push-pull digital output with IO-Link 1.1 (selectable)

3.3 Device view

Device view







Figure 1: Device view, example UC40-11211x

- ① 2 teach-in buttons
- 2 Release button
- ③ Male connector, M12, 5-pin
- ④ 4 status LEDs
- (5) Ultrasonic transducer

Further topics

• Dimensioned drawing

4 Transport and storage

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4.1 Transport

NOTICE Damage due to improper transport!

- The product must be packaged with protection against shock and damp.
- Recommendation: Use the original packaging.
- Note the symbols on the packaging.
- Do not remove packaging until immediately before you start mounting.

4.2 Unpacking

- To protect the device against condensation, allow it to equilibrate with the ambient temperature before unpacking if necessary.
- Handle the device with care and protect it from mechanical damage.

4.3 Transport inspection

Immediately upon receipt in Goods-in, check the delivery for completeness and for any damage that may have occurred in transit. In the case of transit damage that is visible externally, proceed as follows:

- Do not accept the delivery or only do so conditionally.
- Note the scope of damage on the transport documents or on the transport company's delivery note.
- File a complaint.

i NOTE

Complaints regarding defects should be filed as soon as these are detected. Damage claims are only valid before the applicable complaint deadlines.

4.4 Storage

- Do not store outdoors.
- Store in a place protected from moisture and dust.
- Recommendation: Use the original packaging.
- Do not expose to any aggressive substances.
- Protect from sunlight.
- Avoid mechanical shocks.
- Storage temperature: see "Technical data", page 36.
- For storage periods of longer than 3 months, check the general condition of all components and packaging on a regular basis.

5 Mounting

5.1 Mounting instructions

- Observe the technical data.
- To prevent condensation, avoid exposing the device to rapid changes in temperature.
- The mounting site has to be designed for the weight of the device.

5.2 Arranging multiple devices

5.2.1 Mounting distances

Overview

To use multiple devices, observe the following mounting distances. If you undercut the specified mounting distance, activate synchronization or multiplex operation.

Mounting distances

Device type	Parallel	Opposite
UC40-112xxx	> 40 cm	> 250 cm
UC40-113xxx	> 110 cm	> 800 cm
UC40-114xxx	> 200 cm	> 1800 cm

5.2.2 Synchronization and multiplex operation

Important notes



Synchronization and multiplex operation are not available in IO-Link mode.

Synchronization and multiplex operation

In synchronization or multiplex operation, a maximum of 50 devices can be interconnected via pin 5 (MF). Synchronization and multiplex operation prevent mutual interference of several interconnected devices. The detection area increases to the area covered by all interconnected devices.

Synchronization mode

In synchronization operation, all devices send and receive the ultrasonic pulses simultaneously. The device detects objects, but does not record the position of the objects. Synchronization operation starts automatically as soon as the devices are interconnected via PIN 5 (MF).

Multiplex operation

In multiplex operation, all devices transmit and receive the ultrasonic pulses one after the other in a defined sequence. The device detects objects and also determines the position of the objects. To switch to multiplex operation, assign different addresses to the connected devices via SOPAS ET, IO-Link or the Connect+ software.

Further topics

- Activating and deactivating teach-in buttons and synchronization
- Teaching in several synchronized devices

5.3 Alignment of the device



Figure 2: Aligning the device for smooth and rough surfaces

- ① Smooth surface: Angle $\leq 90^{\circ} \pm 3^{\circ}$ between the sensor axis and object surface
- 2 Rough surface: Angle \geq 90° ± 3° between the sensor axis and object surface

5.4 Aligning device with alignment aid

Overview

The alignment aid can be used to align the device with the object during mounting.



• = lit up; \rightarrow = flashing.

Approach

- 1. Loosely fasten the device at the installation location so that the device remains movable.
- 2. Briefly press the T2 pushbutton to start the alignment aid.
- ✓ LED 3 flashes green. The faster LED 3 flashes, the stronger the received signal.
- 3. Align the device at the object at different angles for up to 10 seconds so that the device can determine the maximum signal level.
- ✓ LED 3 flashes or permanently lights up green.
- 4. Align the device so that LED 3 permanently lights up green.
- ✓ LED 3 permanently lights up green.
- 5. Fasten the device in this position.
- 6. To end the alignment aid, press T2 briefly or wait 120 seconds.
- ✓ LED 4 flashes orange twice.
- ✓ The device switches back to normal operation.

5.5 Locking and unlocking release button



5.6 Mounting device

Approach

1. Unlock the device.



2. Remove the device from the clamping bracket with the release button pressed.



3. Swivel or rotate the device.



4. Position the device on the clamping bracket and snap it into place.



6 Electrical installation

6.1 Wiring instructions

Pre-assembled cables can be found on the product page.

The call is made via the SICK Product ID: pid.sick.com/{P/N}/{S/N}

 $\{P/N\}$ corresponds to the part number of the product, see type label.

{S/N} corresponds to the serial number of the product, see type label (if indicated).

NOTICE

Faults during operation and defects in the device or the system

Incorrect wiring may result in operational faults and defects.

Follow the wiring notes precisely.

The enclosure rating stated in the technical data is achieved only with a screwed plug connector or protective cap.

Connect the connecting cables in a de-energized state. Do not switch on the supply voltage until installation is complete and all connecting cables are connected to the device and control.

The supply voltage must be as specified in the technical data, see "Technical data", page 36.

When commissioning, protect the device from moisture and contamination.

6.2 Prerequisites for safe operation of the device



Risk of injury and damage caused by electrical current!

As a result of equipotential bonding currents between the device and other grounded devices in the system, faulty grounding of the device can give rise to the following dangers and faults:

- Dangerous voltages are applied to the metal housings.
- Devices will behave incorrectly or be destroyed.
- Cable shielding will be damaged by overheating and cause cable fires.

Remedial measures

- Only skilled electricians should be permitted to carry out work on the electrical system.
- If the cable insulation is damaged, disconnect the voltage supply immediately and have the damage repaired.
- Ensure that the ground potential is the same at all grounding points.
- Where local conditions do not meet the requirements for a safe earthing method, take appropriate measures. For example, ensure low-impedance and current-carry-ing equipotential bonding.

The device is connected to the peripheral devices (any local trigger sensor(s), system controller) via shielded cables. The cable shield – for the data cable, for example – rests against the metal housing of the device.

The device can be grounded through the cable shield or through a blind tapped hole in the housing, for example.

If the peripheral devices have metal housings and the cable shields are also in contact with their housings, it is assumed that all devices involved in the installation have the **same ground potential**.

This is achieved by complying with the following conditions:

- Mounting the devices on conductive metal surfaces
- Correctly grounding the devices and metal surfaces in the system
- If necessary: low-impedance and current-carrying equipotential bonding between areas with different ground potentials



Figure 3: Example: Occurrence of equipotential bonding currents in the system configuration

- ① System controller
- 2 Device
- ③ Voltage supply
- (4) Grounding point 2
- (5) Closed current loop with equalizing currents via cable shield
- 6 Ground potential difference
- ⑦ Grounding point 1
- ⑧ Metal housing
- Shielded electrical cable

If these conditions are not fulfilled, equipotential bonding currents can flow along the cable shielding between the devices due to differing ground potentials and cause the hazards specified. This is, for example, possible in cases where there are devices within a widely distributed system covering several buildings.

Remedial measures

The most common solution to prevent equipotential bonding currents on cable shields is to ensure low-impedance and current-carrying equipotential bonding. If this equipotential bonding is not possible, the following solution approaches serve as a suggestion.

NOTICE

!

We expressly advise against opening up the cable shields. This would mean that the EMC limit values can no longer be complied with and that the safe operation of the device data interfaces can no longer be guaranteed.

Measures for widely distributed system installations

On widely distributed system installations with correspondingly large potential differences, the setting up of local islands and connecting them using commercially available **electro-optical signal isolators** is recommended. This measure achieves a high degree of resistance to electromagnetic interference.



= 7 = 8 - = 9

Figure 4: Example: Prevention of equipotential bonding currents in the system configuration by the use of electro-optical signal isolators

- ① System controller
- 2 Electro-optical signal isolator
- 3 Device
- (4) Voltage supply
- (5) Grounding point 2
- 6 Grounding point 1
- ⑦ Metal housing
- (8) Shielded electrical cable
- 9 Optical fiber

The use of electro-optical signal isolators between the islands isolates the ground loop. Within the islands, a stable equipotential bonding prevents equalizing currents on the cable shields.

Measures for small system installations

For smaller installations with only slight potential differences, insulated mounting of the device and peripheral devices may be an adequate solution.

Even in the event of large differences in the ground potential, ground loops are effectively prevented. As a result, equalizing currents can no longer flow via the cable shields and metal housing.

The voltage supply for the device and the connected peripheral devices must also guarantee the required level of insulation.

Under certain circumstances, a tangible potential can develop between the insulated metal housings and the local ground potential.

6.3 Pin assignment

UC40-xxxxB



Figure 5: Male connector, M12, 5-pin

Table 2: Pin assignment UC40-xxxxB

Contact	Signs	Wire color	Description
1	L+	Brown	Supply voltage, see "Mechanics/Electronics", page 36
2	N/C	White	Not assigned
3	М	Blue	Supply voltage: 0 V
4	$Q 1/\overline{Q1}/C$	Black	Digital output 1, IO-Link communication
5	MF	Gray	Multifunction input (MF), synchronization and multiplex operation, communication via Con- nect+ software

UC40-xxxxH





Figure 6: Male connector, M12, 5-pin

Table 3: Pin assignment UC40-xxxxH

Contact	Signs	Wire color	Description
1	L+	Brown	Supply voltage, see "Mechanics/Electronics", page 36
2	$Q_A/Q2/\overline{Q2}$	White	Analog output or digital output 2
3	М	Blue	Supply voltage: 0 V
4	$Q1/\overline{Q1}/C$	Black	Digital output 1, IO-Link communication
5	MF	Gray	Multifunction input (MF), synchronization and multiplex operation, communication via Con- nect+ software

7 Operation

7.1 Display and control elements

Overview



6 T2 pushbutton

Status LEDs

Status LED	Color	Status
1	Orange	Pin 2 output status: Operating mode of analog output: on = object outside analog scaling; off = object within analog scaling Digital output operating mode 2: on = active; off = deac- tivated
2	Green	Output 2 operating mode: On = analog output; off = digital output 2
3	Green	Status indicator: On = normal operation; flashing = IO-Link operation
4	Orange	Pin 4 output status: Digital output 1: on = active; off = deactivated

7.2 Note for teach-in

If a teach-in process is not complete, any changes made are discarded after 30 seconds.

7.3 Teach-in via pushbuttons

7.3.1 Setting pin 2 output (UC40-xxxxH only)

Overview

The UC40-xxxxH product type has a second output. For this output, it is possible to choose between automatic current or voltage output and fixed current, voltage or digital output. The desired output must be selected before the teach-in process.

With automatic selection of current or voltage output (factory setting), the device checks the load at the analog output. Depending on the load, the device automatically selects current or voltage output.

Approach

- 1. Switch off the supply voltage.
- 2. Ensure that connected hardware is not damaged by the 24 V output voltage.
- 3. Press and hold the **T2** pushbutton.
- 4. Press and hold the **T2** pushbutton to switch on the supply voltage.
- 5. Press and hold T2 for 6 seconds until LED 4 lights up and LED 3 flashes.
- ✓ LED 4 lights up green.
- ✓ LED 4 flashes orange 1x: device automatically selects current or voltage output (factory setting).
- ✓ LED 4 flashes orange 2x: voltage output.
- ✓ LED 4 flashes orange 3x: current output.
- ✓ LED 4 flashes orange 4x: push-pull digital output.
- 6. To change the setting, press **T2** for 1 second.
- 7. Wait 10 seconds.
- ✓ The pin 2 output is set. The device automatically switches to normal operation mode.

7.3.2 Digital output 1 teach-in

7.3.2.1 Factory settings of the digital output

- N/O contact
- Switching point at maximum operating range

7.3.2.2 Teaching in switching point (Single Point Mode)

Overview

When the object is located below the taught-in switching point, the digital output is active.

Approach

Teaching in the switching point (distance to object as switching point)



- 1. Position the object at ①.
- 2. Press T2 pushbutton for 3 seconds until LED 1 and LED 2 flash simultaneously.
- ✓ LED 1 and LED 2 flash alternately.
- 3. Press **T2** for 1 second.
- ✓ The switching point is taught in. The device automatically switches to normal operation mode.

Teaching in switching point (distance to object + 8% as switching point)

- 1. Position the object at ①.
- 2. Press T2 pushbutton for 3 seconds until LED 1 and LED 2 flash simultaneously.
- ✓ LED 1 and LED 2 flash alternately.
- 3. Press T2 for 3 seconds until LED 1 and LED 2 flash alternately again.
- ✓ The switching point is taught in. The device automatically switches to normal operation mode.

7.3.2.3 Teaching in switching window (Window Mode)

Overview

When the object is located within the taught-in switching window, the digital output is active.

Approach



- 1. Position the object at ①.
- 2. Press T2 pushbutton for 3 seconds until LED 1 and LED 2 flash simultaneously.
- ✓ LED 1 and LED 2 flash alternately.
- 3. Position the object at 2.
- ✓ LED 1 and LED 2 flash alternately.
- 4. Press T2 for 1 second.
- The switching points are taught in. The device automatically switches to normal operation mode.

7.3.2.4 Teaching in background (Window Mode ± 8%)

Overview

When the object is located either below the taught-in background -10 mm (IO-Link: -8%) or above the taught-in background +10 mm (IO-Link: +8%), the digital output is active.

Approach



- 1. Position the background at ①.
- 2. Press T2 pushbutton for 3 seconds until LED 1 and LED 2 flash simultaneously.
- ✓ LED 1 and LED 1 flash alternately.
- 3. Press T2 for 10 seconds until LED 1 and LED 2 stop flashing.
- ✓ The background is taught in. The device automatically switches to normal operation mode.

7.3.2.5 Adjusting the N/C contact and N/O contact

Approach

- 1. Press T2 pushbutton for 13 seconds until LED 1 and LED 2 flash alternately.
- ✓ LED 1 flashes orange.
- \checkmark N/O contact: LED 2 lights up green.
- ✓ N/C contact: LED 2 does not light up.
- 2. To change the setting, press **T2** for 1 second.
- 3. Wait 10 seconds.
- N/C and N/O are adjusted. The device automatically switches to normal operation mode.

7.3.3 Digital output 2 teach-in (UC40-xxxxH only)

7.3.3.1 Factory settings of the digital output

- N/O contact
- Switching point at maximum operating range

7.3.3.2 Teaching in switching point (Single Point Mode)

Overview

When the object is located below the taught-in switching point, the digital output is active.

Approach

Teaching in the switching point (distance to object as switching point)



- 1. Position the object at ①.
- 2. Press T1 pushbutton for 3 seconds until LED 3 and LED 4 flash simultaneously.
- ✓ LED 3 and LED 4 flash alternately.
- 3. Press **T1** for 1 second.
- ✓ The switching point is taught in. The device automatically switches to normal operation mode.

Teaching in switching point (distance to object + 8% as switching point)

- 1. Position the object at ①.
- 2. Press T1 pushbutton for 3 seconds until LED 3 and LED 4 flash simultaneously.
- ✓ LED 3 and LED 4 flash alternately.
- 3. Press T1 for 3 seconds until LED 3 and LED 4 flash alternately again.
- ✓ The switching point is taught in. The device automatically switches to normal operation mode.

7.3.3.3 Teaching in switching window (Window Mode)

Overview

When the object is located within the taught-in switching window, the digital output is active.

Approach



- 1. Position the object at ①.
- 2. Press T1 pushbutton for 3 seconds until LED 3 and LED 4 flash simultaneously.
- ✓ LED 3 and LED 4 flash alternately.
- 3. Position the object at 2.
- ✓ LED 3 and LED 4 flash alternately.

- 4. Press **T1** for 1 second.
- ✓ The switching points are taught in. The device automatically switches to normal operation mode.

7.3.3.4 Teaching in background (Window Mode ± 8%)

Overview

When the object is located either below the taught-in background -10 mm (IO-Link: -8%) or above the taught-in background +10 mm (IO-Link: +8%), the digital output is active.

Approach



- 1. Position the background at ①.
- 2. Press T1 pushbutton for 3 seconds until LED 3 and LED 4 flash simultaneously.
- LED 3 and LED 4 flash alternately.
- 3. Press T1 for 10 seconds until LED 3 and LED 4 stop flashing.
- The background is taught in. The device automatically switches to normal operation mode.

7.3.3.5 Adjusting the N/C contact and N/O contact

Approach

- 1. Press T1 pushbutton for 13 seconds until LED 3 and LED 4 flash alternately.
- ✓ LED 3 flashes orange.
- \checkmark N/O contact: LED 4 lights up green.
- ✓ N/C contact: LED 4 does not light up.
- 2. To change the setting, press T1 for 1 second.
- 3. Wait 10 seconds.
- N/C and N/O are adjusted. The device automatically switches to normal operation mode.

7.3.4 Analog output teach-in (UC40-xxxxH only)

7.3.4.1 Factory settings of the analog output

Rising output characteristic from minimum to maximum operating range

7.3.4.2 Scaling analog output

Overview

To scale the analog output, teach in a close sensor and distant sensor scaling limit. If the distant sensor scaling limit is taught in first and then the close sensor scaling limit, the limits are reversed internally.

Approach

Teaching in the scaling limits



- 1. Position the object at ①.
- 2. Press T1 pushbutton for 3 seconds until LED 1 and LED 2 flash simultaneously.
- ✓ LED 1 and LED 2 flash alternately.
- 3. Position the object at ②.
- 4. Press **T1** for 1 second.
- ✓ The scaling is taught in. The device automatically switches to normal operation mode.

7.3.4.3 Adjusting the rising or falling output characteristic

Approach

- 1. Press operating key T1 for 13 seconds until LED 1 and LED 2 flash alternately.
- ✓ LED 1 flashes orange.
- ✓ LED 2 lights up green: rising output characteristic.
- ✓ LED 2 does not light up: falling output characteristic.
- 2. To change the setting, press **T1** for 1 second.
- 3. Wait 10 seconds.
- ✓ The rising and falling output characteristic are adjusted. The device automatically switches to normal operation mode.

7.3.5 Resetting the device to factory settings

Approach

- 1. Switch off the supply voltage.
- 2. Press and hold the **T2** pushbutton.
- 3. Press and hold the **T2** pushbutton to switch on the supply voltage.
- 4. Press and hold T2 for 13 seconds until LED 3 and LED 4 stop flashing.
- 5. Release **T2**.
- ✓ The device is reset to the factory settings. The device automatically switches to normal operation mode.

7.3.6 Activating and deactivating teach-in buttons and synchronization

Approach

- 1. Switch off the supply voltage.
- 2. Press and hold the **T2** pushbutton.
- 3. Press and hold the **T2** pushbutton to switch on the supply voltage.
- 4. Press and hold **T2** for 3 seconds until **LED 3** and **LED 4** flash simultaneously.
- ✓ LED 1 does not light up.
- ✓ LED 3 flashes orange 1x: teach-in buttons and synchronization are activated (factory setting).
- ✓ LED 3 flashes orange 2x: teach-in buttons are deactivated, synchronization is activated.
- ✓ LED 3 flashes orange 3x: teach-in buttons and synchronization are deactivated.
- ✓ LED 3 flashes orange 4x: teach-in buttons are activated, synchronization is deactivated.
- 5. To change the setting, press **T2** for 1 second.
- 6. Wait 10 seconds.
- \checkmark The setting is accepted. The device automatically switches to normal operation

mode.

7.4 Teach-in via multifunctional input

7.4.1 Setting pin 2 output (UC40-xxxxH only)

Overview

The UC40-xxxxH product type has a second output. For this output, it is possible to choose between automatic current or voltage output and fixed current, voltage or digital output. The desired output must be selected before the teach-in process.

With automatic selection of current or voltage output (factory setting), the device checks the load at the analog output. Depending on the load, the device automatically selects current or voltage output.

Approach

- 1. Switch off the supply voltage.
- 2. Ensure that connected hardware is not damaged by the 24 V output voltage.
- 3. Apply **M** at MF.
- 4. Switch on the supply voltage.
- 5. Wait for 6 seconds until LED 4 lights up and LED 3 flashes.
- LED 4 lights up green
- ✓ LED 4 flashes orange 1x: device automatically selects current or voltage output (factory setting)
- ✓ LED 4 flashes orange 2x: voltage output
- ✓ LED 4 flashes orange 3x: current output
- ✓ LED 4 flashes orange 4x: push-pull digital output
- 6. To change the setting, apply **M** at MF for 1 second.
- 7. Wait 10 seconds.
- The pin 2 output is set. The device automatically switches to normal operation mode.

7.4.2 Digital output 1 teach-in

7.4.2.1 Factory settings of the digital output

- N/O contact
- Switching point at maximum operating range

7.4.2.2 Teaching in switching point (Single Point Mode)

Overview

When the object is located below the taught-in switching point, the digital output is active.

Approach

Teaching in the switching point (distance to object as switching point)



1. Position the object at ①.

- Apply L+ at MF for 3 seconds until both LED 1 and LED 2 are flashing simultaneously.
- ✓ LED 1 and LED 2 flash alternately.
- 3. Apply L+ at MF for 1 second.
- ✓ The switching point is taught in. The device automatically switches to normal operation mode.

Teaching in switching point (distance to object + 8% as switching point)

- 1. Position the object at ①.
- 2. Apply L+ at MF for 3 seconds until both LED 1 and LED 2 are flashing simultaneously.
- ✓ LED 1 and LED 2 flash alternately.
- 3. Apply L+ at MF for 3 seconds until both LED 1 and LED 2 flash alternately again.
- ✓ The switching point is taught in. The device automatically switches to normal operation mode.

7.4.2.3 Teaching in switching window (Window Mode)

Overview

When the object is located within the taught-in switching window, the digital output is active.

Approach



- 1. Position the object at ①.
- Apply L+ at MF for 3 seconds until both LED 1 and LED 2 are flashing simultaneously.
- ✓ LED 1 and LED 2 flash alternately.
- 3. Position the object at ②.
- ✓ LED 1 and LED 2 flash alternately.
- 4. Apply L+ at MF for 1 second.
- The switching points are taught in. The device automatically switches to normal operation mode.

7.4.2.4 Teaching in background (Window Mode ± 8%)

Overview

When the object is located either below the taught-in background -10 mm (IO-Link: -8%) or above the taught-in background +10 mm (IO-Link: +8%), the digital output is active.

Approach



1. Position the background at ①.

- Apply L+ at MF for 3 seconds until both LED 1 and LED 2 are flashing simultaneously.
- ✓ LED 1 and LED 1 flash alternately.
- 3. Apply L+ at MF for 10 seconds until LED 1 and LED 2 stop flashing.
- ✓ The background is taught in. The device automatically switches to normal operation mode.

7.4.2.5 Adjusting the N/C contact and N/O contact

Approach

- 1. Apply L+ at MF for 13 seconds until both LED 1 and LED 2 flash alternately.
- ✓ LED 1 flashes orange.
- ✓ N/O contact: LED 2 lights up green.
- ✓ N/C contact: LED 2 does not light up.
- 2. To change the setting, apply L+ at MF for 1 second.
- 3. Wait 10 seconds.
- ✓ N/C and N/O are adjusted. The device automatically switches to normal operation mode.

7.4.3 Digital output 2 teach-in (UC40-xxxxH only)

7.4.3.1 Factory settings of the digital output

- N/O contact
- Switching point at maximum operating range

7.4.3.2 Teaching in switching point (Single Point Mode)

Overview

When the object is located below the taught-in switching point, the digital output is active.

Approach

Teaching in the switching point (distance to object as switching point)



- 1. Position the object at ①.
- 2. Apply M at MF for 3 seconds until both LED 3 and LED 4 are flashing simultaneously.
- ✓ LED 3 and LED 4 flash alternately.
- 3. Apply **M** at MF for 1 second.
- ✓ The switching point is taught in. The device automatically switches to normal operation mode.

Teaching in switching point (distance to object + 8% as switching point)

- 1. Position the object at ①.
- 2. Apply M at MF for 3 seconds until both LED 3 and LED 4 are flashing simultaneously.
- ✓ LED 3 and LED 4 flash alternately.
- 3. Apply M at MF for 3 seconds until both LED 3 and LED 4 flash alternately again.
- The switching point is taught in. The device automatically switches to normal operation mode.

7.4.3.3 Teaching in switching window (Window Mode)

Overview

When the object is located within the taught-in switching window, the digital output is active.

Approach



- 1. Position the object at ①.
- 2. Apply M at MF for 3 seconds until both LED 3 and LED 4 are flashing simultaneously.
- ✓ LED 3 and LED 4 flash alternately.
- 3. Position the object at 2.
- ✓ LED 3 and LED 4 flash alternately.
- 4. Apply **M** at MF for 1 second.
- The switching points are taught in. The device automatically switches to normal operation mode.

7.4.3.4 Teaching in background (Window Mode ± 8%)

Overview

When the object is located either below the taught-in background -10 mm (IO-Link: -8%) or above the taught-in background +10 mm (IO-Link: +8%), the digital output is active.

Approach



- 1. Position the background at ①.
- 2. Apply M at MF for 3 seconds until both LED 3 and LED 4 are flashing simultaneously.
- ✓ LED 3 and LED 4 flash alternately.
- 3. Apply M at MF for 10 seconds until LED 3 and LED 4 stop flashing.
- ✓ The background is taught in. The device automatically switches to normal operation mode.

7.4.3.5 Adjusting the N/C contact and N/O contact

Approach

- 1. Apply M at MF for 13 seconds until both LED 3 and LED 4 flash alternately.
- ✓ LED 3 flashes orange.
- ✓ N/O contact: LED 4 lights up green.
- ✓ N/C contact: LED 4 does not light up.
- 2. To change the setting, apply **M** at MF for 1 second.
- 3. Wait 10 seconds.
- N/C and N/O are adjusted. The device automatically switches to normal operation mode.

7.4.4 Analog output teach-in (UC40-xxxxH only)

7.4.4.1 Factory settings of the analog output

• Rising output characteristic from minimum to maximum operating range

7.4.4.2 Scaling analog output

Overview

To scale the analog output, teach in a close sensor and distant sensor scaling limit. If the distant sensor scaling limit is taught in first and then the close sensor scaling limit, the limits are reversed internally.

Approach

Teaching in the scaling limits



- 1. Position the object at ①.
- 2. Apply M at MF for 3 seconds until both LED 1 and LED 2 are flashing simultaneously.
- ✓ LED 1 and LED 2 flash alternately.
- 3. Position the object at 2.
- 4. Apply **M** at MF for 1 second.
- ✓ The scaling is taught in. The device automatically switches to normal operation mode.

7.4.4.3 Adjusting the rising or falling output characteristic

Approach

- 1. Apply M at MF for 13 seconds until both LED 1 and LED 2 flash alternately.
- ✓ LED 1 flashes orange.
- ✓ LED 2 lights up green: rising output characteristic.
- ✓ LED 2 does not light up: falling output characteristic.
- 2. To change the setting, apply **M** at MF for 1 second.
- 3. Wait 10 seconds.
- ✓ The rising and falling output characteristic are adjusted. The device automatically switches to normal operation mode.

7.4.5 Resetting the device to factory settings

Approach

- 1. Switch off the supply voltage.
- 2. Apply M at MF.
- 3. Switch on the supply voltage.
- 4. Wait for 13 seconds until LED 3 and LED 4 stop flashing.
- 5. To apply the factory settings, separate **M** from MF before switching off the supply voltage.
- ✓ The device is reset to the factory settings. The device automatically switches to normal operation mode.

7.4.6 Activating and deactivating teach-in buttons and synchronization

Approach

- 1. Switch off the supply voltage.
- 2. Apply **M** at MF.
- 3. Switch on the supply voltage.
- 4. Wait for 3 seconds until both LED 3 and LED 4 are flashing simultaneously.
- ✓ LED 1 does not light up.
- ✓ LED 3 flashes orange 1x: teach-in buttons and synchronization are activated (factory setting).
- ✓ LED 3 flashes orange 2x: teach-in buttons are deactivated, synchronization is activated.
- ✓ LED 3 flashes orange 3x: teach-in buttons and synchronization are deactivated.
- ✓ LED 3 flashes orange 4x: teach-in buttons are activated, synchronization is deactivated.
- 5. To change the setting, apply **M** at MF for 1 second.
- 6. Wait 10 seconds.
- The setting is accepted. The device automatically switches to normal operation mode.

7.4.7 Teaching in several synchronized devices

Important information

i NOTE

When teaching-in via pushbuttons or IO-Link, each device continues to be taught-in individually even in synchronization operation.

Prerequisites

- Several devices are synchronized with each other (synchronization operation).
- Teach-in via multifunction input (pin 5) is activated.

Approach

- Start a teach-in process on one of the synchronized units via the multifunction input.
- \checkmark This teach-in process is started for all synchronized units.

Example

- Teach-in a switching point at a device via the multifunction input (Single Point Mode).
- ✓ For each synchronized device, its current measured value is taught in as the switching point.

7.5 IO-Link

Depending on the product type, the product can exchange process data and parameters via IO-Link. To do this, connect the product to a suitable IO-Link Master. A sensorspecific device description file (IODD) is required in the IO-Link Master. The IODD and a supplementary information document are available on the product page.

The page can be accessed via the SICK Product ID: pid.sick.com/{P/N}/{S/N}

{P/N} corresponds to the part number of the product, see type label.

{S/N} corresponds to the serial number of the product, see type label (if indicated).

7.6 Establishing a connection to SOPAS ET

Overview

The SOPAS Engineering Tool (SOPAS ET) software is suitable for parameterization as well as for service and diagnostics purposes.

Prerequisites

- Product type with IO-Link
- A computer with the SOPAS ET software installed on it, and a free USB 2.0 compatible port

The most up-to-date version of the SOPAS ET software can be downloaded from www.sick.com/SOPAS_ET. The respective system requirements for installing SOPAS ET are also specified there.

- SICK SiLink2 Master (available as accessory)
- Connection cable with M12 male and female connectors, 4-pin (available as accessory)
- Device description file (SDD)

i NOTE

⁷ The SDD can be installed in SOPAS ET or via the SICK website. Follow the instructions in SOPAS ET.

Approach

- 1. Connect the product to the SiLink2 Master via the male connector or an additional connection cable.
- 2. Connect the SiLink2 Master to the computer using the supplied USB cable.
- 3. Switch on and start the computer.
- 4. To ensure an adequate voltage supply to the product, also connect the enclosed wall plug to the SiLink2 Master.
- ✓ The status LEDs light up green after successful initialization. The product is ready for operation.
- 5. Install the device description file.
- 6. Select the product from the device catalog and add it to a project.
- ✓ A connection to the product is established via the communication interface. The connection must be activated for data transmission (online).

8 Maintenance

8.1 Maintenance plan

During operation, the device works maintenance-free.

Table 4: Maintenance plan

Maintenance work	Interval	To be carried out by
Check device and connecting cables for damage at regular intervals.	Depends on ambient conditions and climate.	Specialist
Check the screw connections and plug connectors.	Depends on the place of use, ambi- ent conditions or operating require- ments. Recommended: At least every 6 months.	Specialist

8.2 Cleaning

! NOTICE

Equipment damage due to improper cleaning.

Improper cleaning may result in equipment damage.

- Only use recommended cleaning agents and tools.
- Never use sharp objects for cleaning.
- Carefully clean the adjoining faces with water at regular intervals.

9 Troubleshooting

9.1 Repairs

Repair work on the device may only be performed by qualified and authorized personnel from SICK AG. Interruptions or modifications to the device by the customer will invalidate any warranty claims against SICK AG.

9.2 Returns

- Only send in devices after consulting with SICK Service.
- The device must be sent in the original packaging or an equivalent padded packaging.

i NOTE

To enable efficient processing and allow us to determine the cause quickly, please include the following when making a return:

- Details of the contact person
- Description of the application
- Description of the fault that occurred

9.3 Disposal



Risk of injury due to hot device surface.

The surface of the device can become hot.

- Before performing work on the device (e.g. mounting, cleaning, disassembly), switch off the device and allow it to cool down.
- Ensure good dissipation of excess heat from the device to the surroundings.

If a device can no longer be used, dispose of it in an environmentally friendly manner in accordance with the applicable country-specific waste disposal regulations. Do not dispose of the product along with household waste.

NOTICE

!

Danger to the environment due to improper disposal of the device.

Disposing of devices improperly may cause damage to the environment. Therefore, observe the following information:

- Always observe the national regulations on environmental protection.
- Separate the recyclable materials by type and place them in recycling containers.

10 Technical data

NOTE

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⁷ The relevant online product page for your product, including technical data, dimensional drawing, and connection diagrams, can be downloaded, saved, and printed from the Internet.

The page can be accessed via the SICK Product ID: pid.sick.com/{P/N}/{S/N}

 $\{P/N\}$ corresponds to the part number of the product, see type label.

 $\{S/N\}$ corresponds to the serial number of the product, see type label (if indicated).

Please note: This documentation may contain further technical data.

10.1 Mechanics/Electronics

Supply voltage V _S	DC 9 V 30 V ¹⁾²⁾
Power consumption	\leq 1.5 W ³
Initialization time	< 300 ms
Design	Cuboid
Housing material	plastic (PA66) Ultrasonic transducer: polyurethane foam, epoxy resin
Connection type	Male connector, M12, 5-pin
Display	4 x LED
Weight	UC40-11 2 11x: 120 g UC40-11 3 11x: 120 g UC40-11 4 11x: 130 g
Sending axis	Straight
Dimensions (W x H x D)	40 mm x 40 mm x 66 mm
Enclosure rating	IP65 / IP67
Protection class	III
Scope of delivery	Push-lock mounting system (1x)

1) Limit values, reverse-polarity protected. Operation in short-circuit protected network: max. 8 A, class 2.

 $^{2)}$ $\,$ 15 V ... 30 V when using the analog voltage output.

3) Without load

10.2 Dimensioned drawing

UC40-11211x



Figure 7: Structure and device dimensions, unit of measurement: mm (inch), decimal separator: point

- ① 2 fixing holes; radius: 2.8 mm
- 2 fixing holes; diameter: 5.5 mm

UC40-11311x





Figure 8: Structure and device dimensions, unit of measurement: mm (inch), decimal separator: point

- ① 2 fixing holes; radius: 2.8 mm
- 2 fixing holes; diameter: 5.5 mm

UC40-11411x



Figure 9: Structure and device dimensions, unit of measurement: mm (inch), decimal separator: point

- ① 2 fixing holes; radius: 2.8 mm
- 2 fixing holes; diameter: 5.5 mm

10.3 Performance

UC40-11 2 11x: 65 mm 350 mm UC40-11 3 11x: 200 mm 1,300 mm UC40-11 4 11x: 350 mm 3,400 mm
UC40-11 2 11x: 600 mm UC40-11 3 11x: 2,000 mm UC40-11 4 11x: 5,000 mm
Natural objects
UC40-11 2 11x: ≥ 0.1 mm UC40-11 3 11x: ≥ 1 mm UC40-11 4 11x: ≥ 1 mm
± 0.15% ¹⁾
± 1% ²⁾³⁾
Temperature compensation
UC40-11 2 11x: 64 ms UC40-11 3 11x: 96 ms UC40-11 4 11x: 160 ms
UC40-11 2 11x: 10 Hz UC40-11 3 11x: 7 Hz UC40-11 4 11x: 4 Hz
UC40-11 2 11x: 16 ms UC40-11 3 11x: 24 ms UC40-11 4 11x: 41.6 ms
UC40-11 2 11x: 400 kHz UC40-11 3 11x: 200 kHz UC40-11 4 11x: 120 kHz
Detection ranges
Adjustable switching point modes: switching point (Single Point Mode) / switching window (Window Mode) / background (Window Mode 8%), teachable digital output, parameterizable digital output, invertible digital output, adjustable switch-on delay digital output, teachable analog output, parameterizable analog output, invertible analog output, automatic switching between current and voltage output, analog output switchable to second digital output, synchronization of up to 50 sensors, multiplexing: no mutual interference of up to 50 sensors, adjustable measurement filters: measured value filter / filter strength / foreground suppression / detection range / sensitivity and sound lobe / false echo suppression, teach-in buttons (can be deactivated), reset to factory settings

1) Relative to the current measured value, minimum value \geq resolution.

2) Relative to the current measured value.

 $^{3)}$ $\,$ Temperature compensation can be switched off, not temperature compensated: 0.17% / K.

⁴⁾ Subsequent smoothing of the analog output may increase the response time by up to 200% in some applications.

10.4 Interfaces

IO-Link	IO-Link V1.1 Function: Process data, configuration, diagnostics, data storage
Digital output	Quantity: 1 Type: Push-pull: PNP/NPN ¹⁾ Maximum output current I_A : \leq 100 mA

Combined: digital or analog output ²⁾	UC40-11x11B: not available UC12-11x11H: number: 1
	 Digital output Type: Push-pull: PNP/NPN ¹⁾ Maximum output current I_A: ≤ 100 mA
	Analog output ³) • 4 mA 20 mA: RL ≤ 500 Ω ⁴) • 0 V 10 V: RL ≥ 100 kΩ
Hysteresis	UC40-11211x: 5 mm UC40-11311x: 20 mm UC40-11411x: 50 mm

¹⁾ Push-pull: PNP/NPN: HIGH = $U_V - (< 3 V) / LOW < 3 V$.

²⁾ Type of output is selectable.

3) The device checks the load on the analog output and automatically switches to current or voltage output.

⁴⁾ At 4 mA ... 20 mA and $U_V \le 20$ V max. load $\le 100 \Omega$.

10.5 Ambient data

Ambient operating temperature	-25 °C +70 °C
Storage temperature	-40 °C +85 °C

10.6 Temperature compensation

The internal temperature compensation reaches the optimum operating point after 3 minutes of operation. Temperature compensation is adjusted at the factory to standard mounting conditions with an aluminum mounting bracket and mounting nuts.

Temperature compensation is automatically adjusted to the individual installation situation under the following conditions.

Conditions of automatic adjustment of temperature compensation

- The device is in a cold state.
- Digital output: The digital output is deactivated for approx. 30 minutes.
- Analog output: The analog output delivers a constant value of 11 mA ... 13 mA or 4.4 V ... 5.6 V for approx. 30 minutes.

If the measured value changes in the 30 minutes, the adjustment is canceled. The default parameters or the last adjusted parameters are retained. Automatic adjustment is suitable for installation situations that deviate greatly from standard installation conditions or where high measurement accuracy is required. One example is thermally insulated mounting.

10.7 Detection ranges

UC40-11211x



- ① Detection range in mm (inch)
- 2 Detection range dependent on reflection properties, size, and alignment of the object
- 3 Limiting range
- ④ Operating range
- (5) Example object: aligned plate 10 mm x 10 mm
- 6 Example object: cylindrical bar with a diameter of 10 mm

UC40-11311x



- ① Detection range in mm (inch)
- 2 Detection range dependent on reflection properties, size, and alignment of the object
- 3 Limiting range
- (4) Operating range
- (5) Example object: aligned plate 10 mm x 10 mm
- 6 Example object: cylindrical bar with a diameter of 10 mm

UC40-11411x



- ① Detection range in mm (inch)
- 2 Detection range dependent on reflection properties, size, and alignment of the object
- 3 Limiting range
- (4) Operating range
- (5) Example object: aligned plate 10 mm x 10 mm
- 6 Example object: cylindrical bar with a diameter of 10 mm

11 Accessories



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On the product page you will find accessories and, if applicable, related installation information for your product.

The page can be accessed via the SICK Product ID: pid.sick.com/{P/N}/{S/N}

 $\{P/N\}$ corresponds to the part number of the product, see type label.

{S/N} corresponds to the serial number of the product, see type label (if indicated).

12 Annex

12.1 Declarations of conformity and certificates

You can download declarations of conformity and certificates via the product page.

The page can be accessed via the SICK Product ID: pid.sick.com/{P/N}/{S/N}

{P/N} corresponds to the part number of the product, see type label.

{S/N} corresponds to the serial number of the product, see type label (if indicated).

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